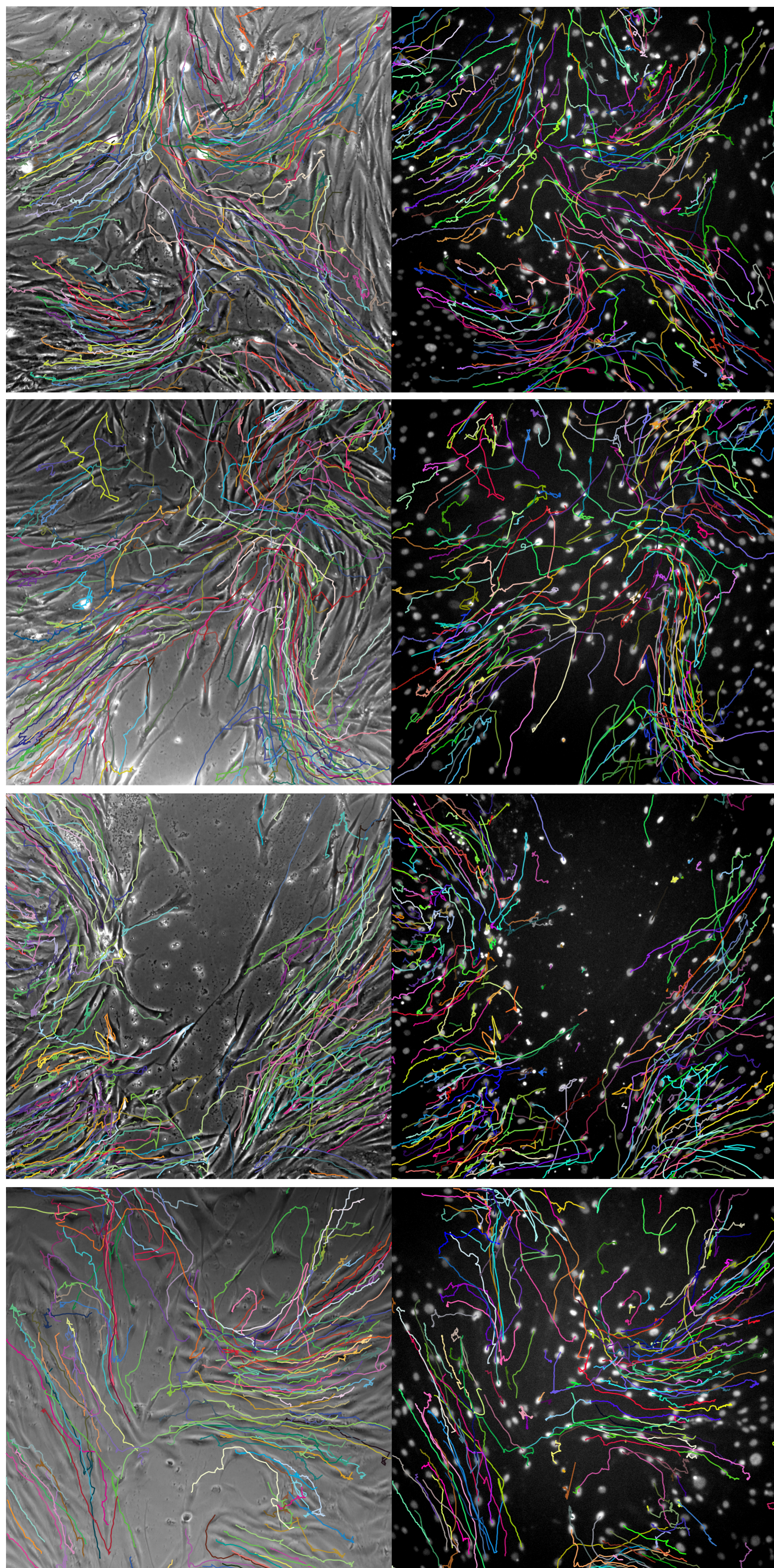


A

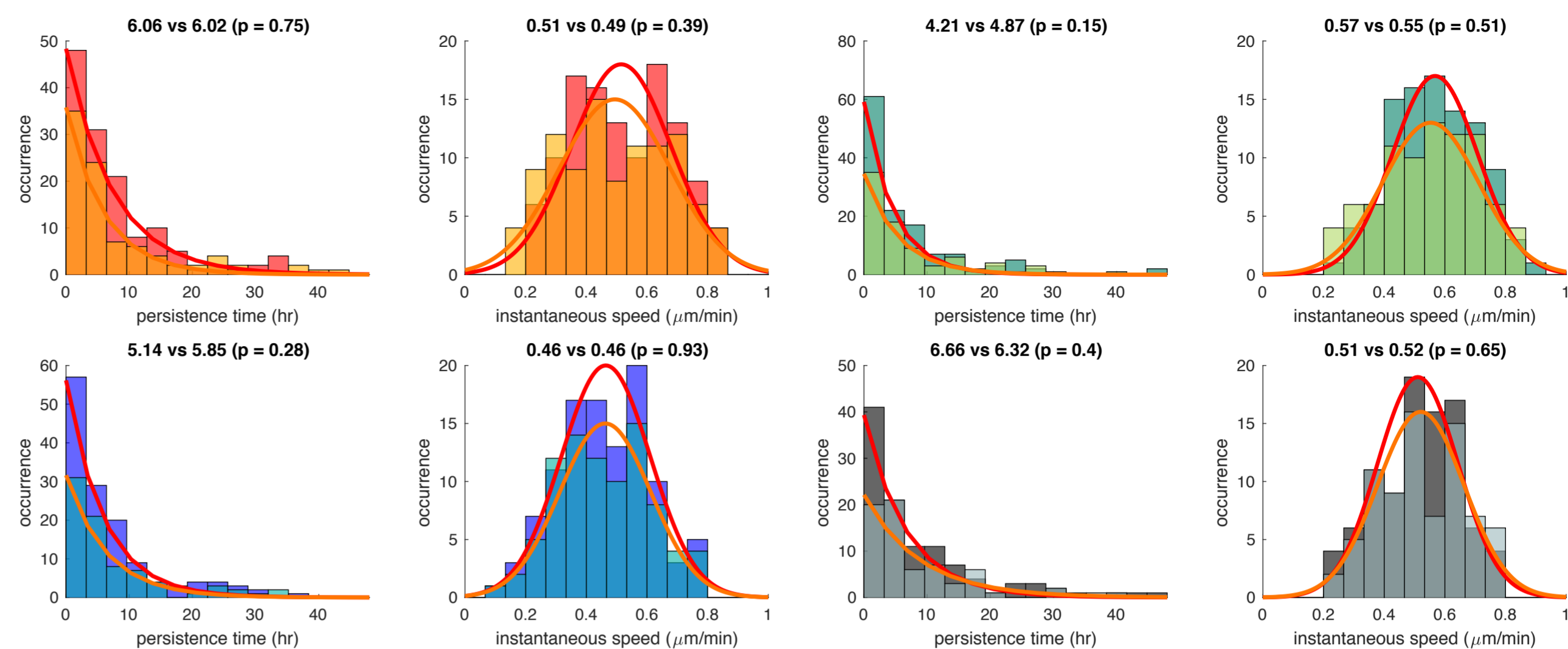
manual

automated



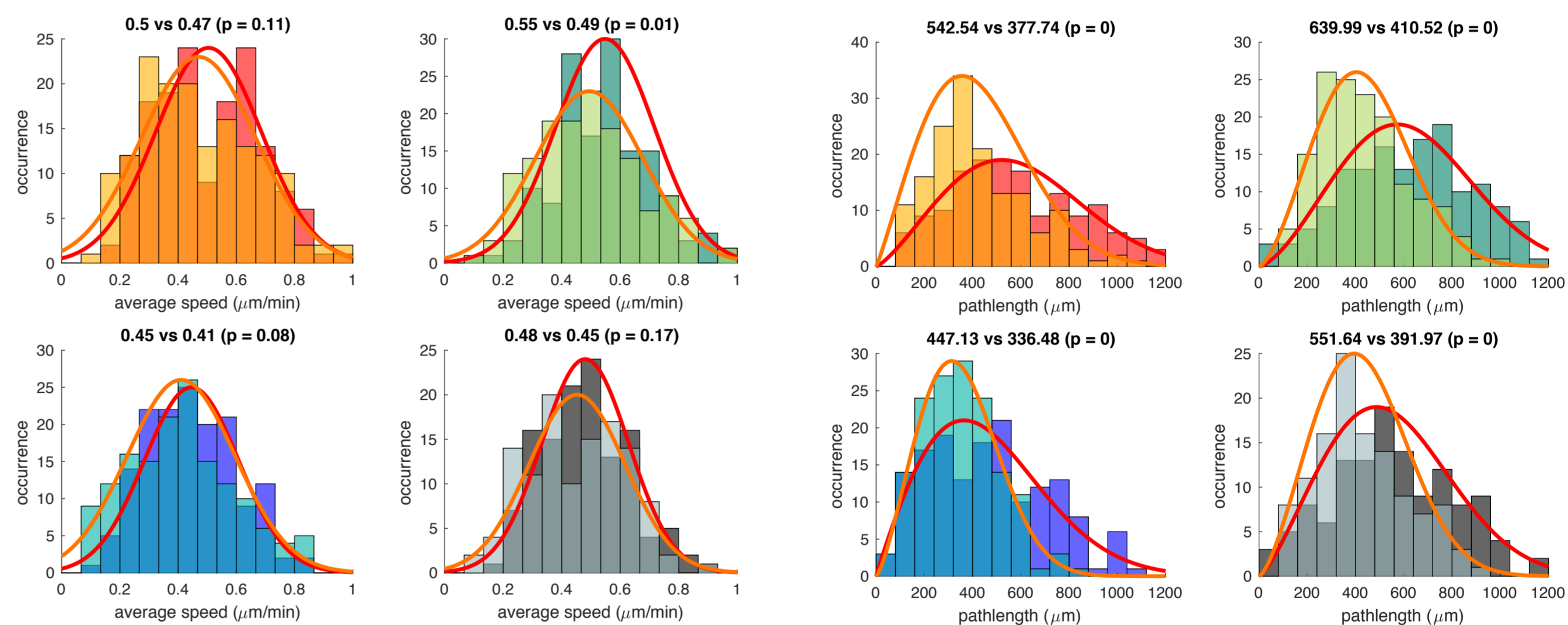
B

persistent random walk parameters



average speed

pathlength



displacement

correction for true average speed

